1	1.	A template comprising:		
2		a plurality of adjacent parallel pins forming an array,		
3		a pin sleeve for engaging and slideably holding the pins in the array,		
4		the pin sleeve having a locking mechanism to fix the pins in their relative		
5	posit	ions when desired,		
6		a flexible track attached to a first end of the pins for forming a closed loop		
7	temp	late, the track having a first fixed end and a second free end, the first fixed end being		
8	taper	ed to create a smooth joint as it forms the closed loop with the second free end, so as		
9	to all	ow for the adjustability of the length of the track, as the pins are moved relative to		
10	each	other.		
1	2.	A template as in claim 1 wherein,		
2		the plurality of pins are cylindrically arrayed.		
3				
1	3.	A template as in claim 2 wherein,		
2		the pin sleeve has a guide for attaching a tool to move along the pin sleeve.		
3		·		
1	4.	A template as in claim 2 wherein,		
2		the template is attached to a cylinder,		
3		a tool rotatably attached to the cylinder, the tool having an arm for engaging the		
4	track	track on the template such that the tool can follow the track on the template as it rotates		
5	on the	e cylinder.		
6				
1	5.	A template as in claim 4 wherein,		
2		the arm is magnetically attracted to contact the track on the template.		
3				
1	6.	A template as in claim 5 wherein,		
2		the arm has a spring for urging the arm contact with the track on the template.		
3				

1			
1	7.	A template as in claim 1 wherein,	
2		the pin sleeve comprises connectable segments with each segment is connected to	
3	other	segments for adjusting the pin sleeve length.	
4			
1	8.	A template as in claim 1 wherein,	
2		the pin sleeve has an engagement mechanism to attach it to an object.	
1			
1			
1	9.	A template as in claim 1 wherein,	
2		the pin sleeve is flexible so it can be shaped to an object.	
3			
1	10. A template as in claim 2 wherein,		
2		the sleeve is in the form of a tubular pantograph mechanism, allowing the pin	
3	sleeve	e to have an adjustable diameter to fit different pipe sizes.	
4			
1	11.	A template as in claim 2 wherein,	
2		a self centering mechanism centers the template on a cylindrical object to which it	
3	is atta	ched.	
4			
1	12.	A template as in claim 1 wherein,	
2		the track has a magnetic material for attracting and engaging an arm on a tool for	
3	guidir	ng the tool.	
4			
1	13.	A template as in claim 1 wherein,	
2		the track has a wire for creating an electromagnetic field for attracting and	
3	engaging an arm on a tool for guiding the tool.		

14

1

3

4

11

17. A method of forming templates for tools as in claim 16 further comprising the

2 step of:

> attaching a work tool having an arm for following the template to the pin sleeve, such that the tool can work on a workpiece by following the template.

5

7

	10 4 1 1 00 1 4 1 0 4 1 1 4 0 1	
1	18. A method of forming templates for tools as in claim 16 further comprising the	
2	step of:	
3	holding a plurality of pins in a pin sleeve which fixes the pins in a radial position	
4	around a center line such that the pins form a cylinder,	
5	forming a template of the pins by placing the pins around a component, of a pipe	
6	to pipe assembly to be welded, and allowing the pins to register the shape of the seamline	
7	to be welded;	
8	locking the pins in position relative to the pin sleeve such that the pins remains	
9	fixed in position,	
10	sliding the template back from the seamline of the connection, and locking it in	
11	position,	
12	attaching a smooth faced adjustable length flexible track to one end of the	
13	plurality of pins,	
14	attaching a welder having a tracing arm to a guide built into the template,	
15	using the track on the template to guide the tracing arm to weld the seamline of	
16	the connecting pipes.	
17		
1	A method of forming templates for tools as in claim 16 further comprising the	
2	step of:	
3	attaching a work tool, having an adjustable length arm mechanism and a motion	
4	system, to a workpiece, such that the tool can work on the work piece by allowing the	
5	adjustable arm mechanism to follow the template while the motion system allows the	
6	work tool to maintain its relative orientation and distance to the surface work piece.	

controlling the axial position of the tool by the template guiding the axial position

1

5

6

7

tool carriage,

of the tool arm relative to the tool carriage.

1